

A vector $\vec{u}$ or $\overrightarrow{A B}$ is an oriented segment having two extremities, an origin and an end point.


## Properties of a vector:

In elementary mathematics, a vector is a geometric object defined by its properties:
a) Direction: the line that holds $\overrightarrow{A B}$ or every line parallel to $(A B)$; egg. vertical, along line $(d) \ldots$
6) Sense: orientation from an initial point to a final point; erg. left to right or from $A$ to $B \ldots$
c) Magnitude: modulus or norm $\|\overrightarrow{A B}\|$ of the given vector is the distance between $A \& B$.

## Representation of a vector:

A vector is frequently represented by a segment with a definite direction, or graphically as an arrow, connecting an initial point $A$ with a terminal point $B$, and denoted by $\overrightarrow{A B}$.


## Special forms of Vectors?

## a) Zero Vector:

Def: Is a vector whose origin and extremity are confounded and it is also known as a null vector.
Notation: A zero vector is denoted by: $\overrightarrow{0}$ or $\overrightarrow{A A}=\overrightarrow{R R}=\overrightarrow{N N}=\vec{O}$
Properties: A zero vector has a zero modullus $\|\overrightarrow{0}\|$ and no definite direction.
b) Unit Vector: is any vector whose magnitude is equal to the chosen unit (scale).
$\boldsymbol{E g}$ : In the figure to the right $\vec{i} \& \vec{j}$ represent the unit vectors of $x$-axis \& $y$ - axis respectively, where $\|\overrightarrow{i \|}\|=\|\vec{j}\|=1$ unit


## Relating vectors:

is Equal vectors:

| Analytic approach | Geometric approach | Conclusion |
| :---: | :---: | :---: |
| Any two vectors $\vec{u}$ and $\vec{v}$ are equal if they have: <br> - Same direction. <br> - Same sense. <br> - Same magnitude. |  | Therefore, vectors $\vec{u}$ and $\vec{v}$ are equal |

## $\checkmark$ Significance of equal vectors:

a. If $\overrightarrow{A B}=\overrightarrow{C D}$, then $C$ is the fourth vertex of the parallelogram $A B D C$.


Conversely: If $A B D C$ is a parm then, $A B=C D$.
b. If $\overrightarrow{A B}=\overrightarrow{C D}$, then the points $A, B, C$ and $D$ are collinear.

c. If $A B=C D$, then the segments $[A D]$ and $[B C]$ have the same midpoint.

\& Opposite Vectors:

| Analytic approach | Geometric approach | Conclusion |
| :---: | :---: | :---: |
| Any two vectors $\vec{u}$ and $\vec{v}$ are opposite if they have: <br> - Same direction. <br> - Same magnitude. <br> - But opposite senses. |  | Therefore, $\vec{u}$ and $\vec{v}$ are opposite. |

## Significanceof opposite vectors is the same as equal vectors

$\star$ Collinear vectors:
Vectors are collinear if and only if they have same direction: means $\left\{\begin{array}{l}\text { held by samest.line }\end{array}\right.$ held by parallel st.lines. In other words, two non-zero vectors $\vec{u} \& \vec{v}$ are collinear if they satisfy the vector relation:

$\left.$| Refation | Meaning |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\vec{u}=k \vec{v}$ | If $k=1$ then | If $k=-1$ then | If $k>1$ then | If $k<1$ then |
|  | $\vec{u} \& \vec{v}$ are equal <br> vectors | $\vec{u} \& \vec{v}$ are <br> opposite vectors | $\vec{u} \& \vec{v}$ have same |  |
| sense |  |  |  |  |$\quad$| $\vec{u} \& \vec{v}$ have |
| :---: |
| opposite senses | \right\rvert\,

## (4) Types of vectors:

|  | Free vectors | Vectors of the same origin | Consecutive Vectors |  |
| :--- | :--- | :--- | :--- | :--- |
| Definition | Are vector having neither a <br> common origin nor common <br> extremity. | Are vector having a <br> common origin only. | Are vectors having the <br> extremity of the first as <br> the origin of the second. |  |
| Geometric <br> approach | $R$ |  |  |  |

## Sum of two vectors:

There are two main methods to add two or more vectors having the same coefficients:

|  | $1^{\text {st }}$ - Method | $2^{\text {nd }}$ - M Method |
| :---: | :---: | :---: |
|  | Parallelogram Rule | Chasles' Rule |
| Used | If vectors have the same origin | If vectors are consecutive |
| Method | Complete the parallelogram | Join the first origin to the last extremity. |
| Graphical representation |  |  |
| Analytical approach | The sum of two vectors with same origin; is a vector with same origin and its extremity is the fourth vertex of the parm. $\overrightarrow{R F}+\vec{R} K=\underline{R} \underbrace{\vec{N}}_{\text {thVertex }}$ | The sum of two consecutive vectors; is a vector with orgin of $1^{\text {st }}$ and extremity of the last. $\overrightarrow{\overrightarrow{A B}}+\overrightarrow{B C}=\underline{\underline{A C}} \underline{\underline{C}} .$ |

## 4. Properties of vector addition:

| $\mathcal{N}$ o. | Analytic approach | Geometric approach |
| :---: | :---: | :---: |
| 1. | Commutativity: <br> Since, $\left.\begin{array}{r} \vec{u}+\vec{v}=\overrightarrow{A C} \\ \vec{v}+\vec{u}=\overrightarrow{A C} \end{array}\right\} \operatorname{so,~\vec {u}+\vec {v}=\vec {v}+\vec {u}}$ |  |
| 2. | Associativity: <br> Since, $\left.\begin{array}{c}\vec{u}+\vec{v}=\overrightarrow{A C} \\ \overrightarrow{A C}+\vec{w}=\overrightarrow{A D}\end{array}\right\}$ then, $(\vec{u}+\vec{v})+\vec{w}=\overrightarrow{A D}$ <br> Since <br> Thus, $(\vec{u}+\vec{v})+\vec{w}=\vec{u}+(\vec{v}+\vec{w})$ |  |

## 4) Triangular inequality:

In any triangle $A B C$ we have:

$$
\|\vec{a}\| \leq \vec{b}\|+\| \vec{c} \|
$$

But, $\vec{b}+\vec{c}=\vec{a}$
So, $\|\vec{b}+\vec{c}\| \neq\|\vec{a}\|$
Thus, $\|\vec{b}+\vec{c}\| \leq\|\vec{b}\|+\|\vec{c}\|$

$\mathcal{H}$ ow to find the Image or translation of some geometric figures


## $\stackrel{\rightharpoonup}{4}$ Properties of translation:

## Transfation preserves:

$\qquad$
Collinearity

If $\boldsymbol{I}$ is the midpoint of $[A B]$ then;

|  | Analytic approach | Graphical representation |
| :---: | :---: | :---: |
| 1- | $\overrightarrow{A I}=\overrightarrow{I B}$ |  |
| 2- | $\overrightarrow{I A}+\overrightarrow{I B}=\overrightarrow{0}$ |  |
| 3- | $\overrightarrow{A B}=2 \overrightarrow{A I}$ |  |
| 4- | $\overrightarrow{A B}=2 \overrightarrow{I B} .$ |  |

is Conversely:
If $\left\{\begin{array}{l}\overrightarrow{A I}=\overrightarrow{I B} \\ \overrightarrow{I A}+\overrightarrow{I B}=\overrightarrow{0} \\ \overrightarrow{A B}=2 \overrightarrow{A I} \\ \overrightarrow{A B}=2 \overrightarrow{I B}\end{array}\right\}$ then, I is the midpoint of $[\boldsymbol{A B}]$

## *) Xedians and Vectors:

If $[A N]$ is a median relative to $[B C]$ then; $\overrightarrow{A B}+\overrightarrow{A C}=2 \overrightarrow{A N}$.

\& Conversely: If $\overrightarrow{A B}+\overrightarrow{A C}=2 \overrightarrow{A N}$ then, $[A N]$ is the median relative $[\boldsymbol{B C}]$.
is Genrerally: If $A$ is any point in the plane and $M$ is the midpoint of $[B C]$ then we write:


## Centroid and Vectors:

If $\boldsymbol{G}$ is the center of gravity (Centroid) of triangle $\boldsymbol{A B C}$ then:

$\overrightarrow{A G}=\frac{2}{3} A \vec{M}$
$\overrightarrow{G M}=\frac{1}{3} \overrightarrow{A M}$
$A \vec{G}=2 \overrightarrow{G M}$

$\overrightarrow{G A}+\overrightarrow{G B}+\overrightarrow{G C}=\overrightarrow{0}$

## Proof:

$\overrightarrow{G B}+\overrightarrow{G C}=2 \overrightarrow{G M}$ (Midpoint of a segment)
But, $2 G M=-G A$
Thus, $\overrightarrow{G A}+\overrightarrow{G B}+\overrightarrow{G C}=\overrightarrow{0}$
is Conversely: If $\overrightarrow{G A}+\overrightarrow{G B}+\overrightarrow{G C}=\overrightarrow{0}$ then; $\boldsymbol{G}$ is the center of gravity of triangle $\boldsymbol{A B C}$.
\& Genreralfy: If $M$ is any point of the plane where $G$ is the centroid of $\triangle A B C$ then we can write:
$\overrightarrow{M A}+\overrightarrow{M B}+\overrightarrow{M C}=3 \overrightarrow{M G}$
Proof: Since $G$ is the centroid of $\triangle A B C$ then
$\overrightarrow{G A}+\overrightarrow{G B}+\overrightarrow{G C}=\overrightarrow{0}$ (Introduce point $M$.)

$$
G \vec{M}+\overrightarrow{M A}+\overrightarrow{G M}+\overrightarrow{M B}+\overrightarrow{G M}+\overrightarrow{M C}=\overrightarrow{0}
$$

So, $3 \overrightarrow{G M}+\overrightarrow{M A}+\overrightarrow{M B}+\overrightarrow{M C}=\overrightarrow{0}$

$$
\overrightarrow{M A}+\overrightarrow{M B}+\overrightarrow{M C}=-3 \overrightarrow{G M}
$$

Therefore;


